PEN Series

Photo Sensor

- · Long distance detection
- IP 64 structure
- Stable LED
- Applied the inverter light noise preventing circuit (B Type)



Suffix code

Model	Code	Description	
PEN-		Photo Sensor	
Sensing method	T 10	Through-beam	10 m
and	M 5	Retro-reflection	0.1 - 5 m
Sensing distance	R 700	Diffuse reflection	700 mm
Power supply voltage		24 - 240 V AC/DC ±10 % 50/60 Hz	
		12 - 24 V DC ±10 %	

Photo Sensor

Specification

Model	Power built in				
Model	PEN-T10A	PEN-M5A	PEN-R700A		
Sensing method	Through beam type	Retro reflection type	Diffuse reflection type		
Sensing distance	10 m	0.1 \sim 5 m	700 mm		
Sensing object	min Ø20 mm (Opaque body)	min Ø60 mm (Opaque body)	200X200 mm (White non-glossy paper)		
Power supply voltage	24 - 240	V AC/DC (Dual usage) ±10 %	50/60 Hz		
Power	Emitter: max 1 W		2 W		
consumption	Receiver: max 2 W	max	2 W		
Operation mode	Light ON	/ Dark ON * Selectable by	mode V/R		
Sensitivity adjustment	— Built in the sensitivity control V/R		itivity control V/R		
Combinal autaut	Relay output (Contact composition 1a, 1b) - Contact capacity: 30 V DC 5 A / 250 V AC 5 A Resistive load				
Control output	Rated load life expectancy - min 100 thousand times				
Response time	max 20 ms				
Hysteresis	Less than 20% of the sensing di		Less than 20% of the sensing distance		
Light source	Infrared lightening LED (Alternation type)		type)		
	Control output indicator: Red LED, stable output indicator: green LED		cator : green LED		
LED	(Red LED of	(Red LED of through beam type emitter is the power indicator)			
Material	Case: Heat resistance ABS, Lens: P.C				
Protective circuit	-				
Connection method	Cable extended type (Number of wire: 5P, Diameter: Ø 6 mm, Length: 2 mm) * Emitter 2P				

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Ambient illumination Sunlight: max 11000 Lux, Incandescent lamp: max 3000 Lux	
Ambient temperature	-20 \sim 65 °C (surrounding storage temperature : -25 \sim 70 °C)
Ambient humidity	35 \sim 85 % RH (with no condensation)
Protective structure	IP 64 (IEC)
Vibration resistance	10 - 55 Hz double amplitude 0,75 mm, for 2 hours each in X, Y and Z directions (But within the power-off state)
Dielectric strength	1,000 V AC (50/60 Hz for 1 min)
Shock resistance	500 % (Approx. 50 G), 3 times each in X, Y and Z directions
Insulation resistance	min 20 $\mbox{M}\mbox{\ensuremath{\Omega}}$ (500 V DC mega between the charging part and case)

Madal	Amp built in				
Model	PEN-T10B	PEN-M5B	PEN-R700B		
Sensing method	Through beam type	Retro reflection type	Diffuse reflection type		
Sensing distance	10 m	0.1 ~ 5 m	700 mm		
Sensing object	min Ø20 mm (Opaque body)	min Ø60 mm (Opaque body)	200X200 mm (White non-glossy paper)		
Power supply voltage		12 - 24 V DC ±10 %			
Current	Emitter: max 35 mA		4E A		
consumption	Receiver: max 20 mA	max	45 mA		
Operation mode	Light ON /	Dark ON * Selectable by th	e mode V/R		
Sensitivity adjustment	_	Built in the sens	itivity control V/R		
Control output	NPN/PNF	open collector output asynch	nronously		
Control output	Load current : Max. 150 mA	DC (Resistive load), Remaining	voltage: Less than 1 V DC		
Response time		max 1 ms			
Hysteresis	_	_	Less than 20 % of the sensing distance		
Light source	Infrared lightening LED (Alternation type)				
. 50	Control output indicator: Red LED, stable output indicator: green LED				
LED	(Red LED of thr	(Red LED of through beam type emitter is the power indicator)			
Material	Cas	e : Heat resistance ABS, Lens	: P.C		
Protective circuit	Built in the reversed power supply conn	ection protective circuit, short protective circu	uit and inverter light noise protective circuit,		
Connection method	Code extended type (Number of wires: 4P, Diameter: Ø 6 mm, Length: 2 mm) * Emitter 2P				
Ambient illumination	Sunlight: max 11000 Lux, Incandescent lamp: max 3000 Lux				
Ambient temperature	-20 \sim 65 °C (Surrounding storage temperature : -25 \sim 70 °C)				
Ambient humidity	$35 \sim 85$ % RH (With no condensation)				
Protective structure	IP 64 (IEC)				
Vibration resistance	0 - 55 Hz double amplitude 0.75 mm, for 2 hours each in X, Y and Z cirections (But with the state wher power being OFF)				
Dielectric strength	1,000 V AC (50/60 Hz for 1 min)				
Shock resistance	500 № (Approx. 50 G), 3 times each in X, Y and Z directions				
Insulation resistance	min 20 M Ω (500 V DC mega between the changing part and case)				

Note 1) The sensing distance can be varied depending on the size, surface condition, glossy, non-glossy of the sensing object

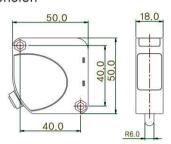
(Note 2) In case of the through beam type, it is a set of the PEN-TL10 \square , emitter, and PEN-TR10 \square , receiver (\square : Power suppl voltage selection, A or B)

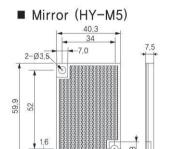
(Note 3) Sensing range of PEN-M5A (B) is a distance when HY-M5 (Mirror) is used



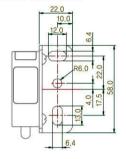
Dimension (Unit: mm)

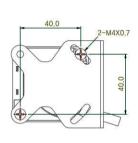
■ Dimension





■ Bracket installed

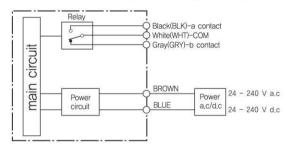




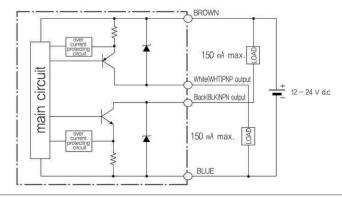


Connection diagram

■ PEN - A (Through beam type only uses the receiver)



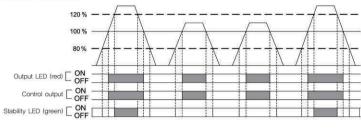
■ PEN - B (Through beam type only uses the receiver)



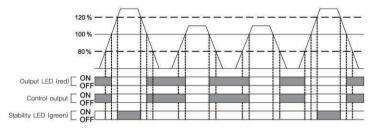
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Operation chart



L.ON operation



D.ON operation

- How to install

■ Through beam type

Order	Installation method	Set image	Output mode
1	Supply in the power after placing the emitter and receiver to face each other in the straight line	Receiver Emitter	
2	Fix either the emitter or receiver and check for the range where output indicator becomes turned OFF by controlling the other in the direction of up, down, left and right. After finishing the confirmation, place it in the middle and fix it.	Receiver	Dark ON
3	Place the sensing object within the setting range and confirm the condition of proper operation and once the confirmation is finished, fix the sensor.	- Emitter	

■ Retro reflection type

Order	Installation method	Set image	Output mode
1	Supply in the power after placing the sensor and mirror to face each other in the straight line	Mirror	
2	Fix either the sensor or mirror and check for the range where output indicator becomes turned OFF by controlling the other in the direction of up, down, left and right. After finishing the confirmation, place it in the middle and fix it.	Mirror	Dark ON
3	Place the sensing object within the setting range and confirm the condition of proper operation and once the confirmation is finished, fix the sensor.	Mirror Emitter	

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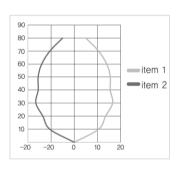
■ Diffusion reflection type

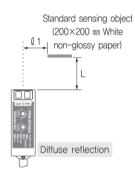
Order	Installation method	Set image	Sensitivity volume	Output mode
1	After removing the sensing object, turn sensitivity volume gradually to the max direction and once operation indicator lights up, that position will be referred as 'A' from now on. (If the indicator does not get turned ON even in the position of maximum then it is max)	Sensor object	Min. Max.	
2	Place the sensing object in the desirable setting position and gradually turn the sensitivity volume from 'A' to the 'Min' direction and once the indicator gets to turned OFF than that position will be referred as 'B'.	Sensor Detecting object	Min. 'B'	Light ON
3	Place the sensitivity volume in the middle of max sensitivity and 'A' confirm the operation condition of sensing object that occurs within the setting range After that fix the sensor.	Detecting object Sensor	Min. B'B'	

Characteristic of sensing range

■ PEN-R700A / PEN-R700B

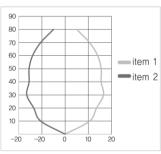
Distance(cm)	Unit(mm)	
0	0	0
10	10.5	-10.5
20	13.5	-13.5
30	16,5	-16.5
40	15.5	-15.5
50	15.5	-15.5
60	14	-14
70	10.5	-10.5
80	5	-5

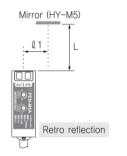




■ PEN-M5A / PEN-M5B

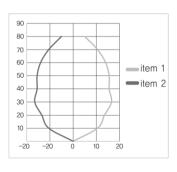
Distance(cm)	Unit(mm)	
0	0	0
1	11	-11
2	16.7	-16.7
3	47.2	-47.2
4	70.9	-70.9
5	115.5	-115.5
6	112.8	-112.8





■ PEN-T10A / PEN-T10B

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Distance(cm)	Unit(mm)	
0	0	0
1	111.5	-111.5
2	215,3	-215,3
3	286.7	-286.7
4	332.6	-332.6
5	296.3	-296.3
6	286.5	-286.5
7	244.7	-244.7
8	288.2	-288.2
9	307.2	-307.2
10	332.2	-332.2
11	347.6	-347.6



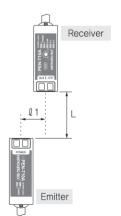


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